



Profibus DP Interface UserGuide

This option module is specifically designed to be used with the BFI-P2/ H2/ H3 of variable speed drive products and is intended for professional incorporation into complete equipment or systems. If installed incorrectly it may present a safety hazard. Before commencing installation and commissioning, the user should ensure they are fully familiar with the BFI-P2/ H2/ H3, and in particular have read the important safety information and warnings contained in the BFI-P2/ H2/ H3 User Guide.

This User Guide is intended to be used with BFI-P2/ H2/ H3 firmware version 1.30 or later. The firmware version of the drive can be displayed in parameter P0-28. Previous versions of firmware can be upgraded using BFI-Tools PC software. Contact Beijer Electronics for further Information.

Overview

The Profibus DP Interface is intended to be installed in the BFI-P2/ H2/ H3 option slot, and allows the BFI to be connected to a Profibus DP network. The interface offers the following functionality :-

- Automatic Baud Rate Detection from 9.6kpbs to 12mbps
- Cyclic Process Data Exchange
- 4 Input Words from the network master to the BFI
- 4 Output Words from the BFI to the network master
- Parameter Access via DPV-1 Read / Write Services

Installation

- Ensure the drive power is removed prior to installing the option module
- Remove the blanking cover from the option module slot
- Carefully slide the option module into the slot, ensuring that the locating tabs are correctly aligned. Do not use excessive force
- Tighten the 2 clamping screws to secure the module in place

BFI Setup

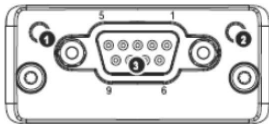
- Set the drive to Fieldbus control mode by setting parameter P1-12 = 4
- Ensure Advanced Parameter Access is enabled on the drive by setting P1-14 = 101
- Set the required node address for the drive in P5-01
- Further drive parameter setting options are possible, please read the BFI-P2/ H2/ H3 User Guide for further information

GSD File

Please obtain it from www.beijer.se or www.beijerelectronics.com

PLC Configuration

Configuration of the PLC varies between different systems. When configuring the Profibus network in the PLC, it is important to ensure that the output data sent from the PLC to the drive is in a lower slot number than the input data from the drive back to the PLC. Refer to information on the specific PLC system in use for further guidance

Item		
1	Operation Mode	
2	Status	
3	Profibus Network Connector	
Operation Mode		
State	Indication	
Off	No Power / Not inserted	
Green	Online, Data Exchange	
Flashing Green	Network OK, No data exchange	
Single Red Flash	Parameter Error	
Double Red Flash	Network Error	
Status		
State	Indication	
Off	No Power	
Green	Initialised	
Flashing Green	Initialised, self-testing	
Red	Error	
Profibus DP Connector Pinnout		
Pin	Function	
1	N/C	
2	N/C	
3	B Line Positive RxD/TxD, RS485 level	
4	RTS (Request to send)	
5	GND Bus ground (isolated)	
6	+5V Bus Output termination power (isolated, short-circuit protected)	
7	N/C	
8	A Line Negative RxD/TxD, RS485 level	
9	N/C	

Data Mapping

BFI-P2/ H2/ H3 support a 4 word cyclic data exchange format. The format and data contained in each word is detailed below.

Input Data (PDI) Telegram

This part of the memory contains the real-time drive commands sent from the network master to the BFI, allowing the BFI to be controlled. The function of the first two data words (PDI 1 and PDI 2) is fixed, to allow basic control over the drive operation and output frequency to be achieved. The configuration of the remaining two words can be adjusted by the user.

PDI Word 1: Fixed Function : Drive Control Word

A 16 Bit control word is used to control the behaviour of the drive when P1-12 = 4. The bits function as follows :-

Bit	Name	Description	
0	Drive Run	0 : Drive Stop 1 : Drive Run	For normal operation, Bit 3 has the highest priority, bit 0 has the lowest priority (bit 3>bit 1>bit 0). For normal run/stop control, Bit 0 only should be used. Note that the start/stop (bit 0), fast stop (bit 1) and coast stop (bit 3) can only be used to control the drive when P2-31= 0 to 3. If P2-37 > 3, the start/stop function is controlled directly by the drive control terminals. The Reset function (bit 2) will operate providing that the drive is set for Fieldbus control P1-12 = 4.
1	Fast Stop Select	0 : No Function 1 : Drive Stop with Deceleration Ramp 2	
2	Fault Reset	0 : No Function 1 : Rising Edge fault reset request	
3	Coast Stop	0 : No Function 1 : Drive Coasts to stop. Overrides bit 0	
4-15	Not Used		

PDI Word 2: Fixed Function : Frequency Setpoint

This word is used to transfer the frequency setpoint to the BFI. The input data is a 16bit signed integer including one decimal place. For example, a value of 500 represents a frequency setpoint to the BFI of 50.0Hz, value 123 gives 12.3Hz. For a negative (reverse) speed reference, a negative value can be transferred to the drive, where the MSB of the high byte must be 1. For example, -1(0xFFFF) gives -0.1Hz. -234(0xFF16) gives -23.4Hz.

The allowed input value range is from -5000 to +5000; however the drive output speed will be limited by the maximum speed set by P1-01.

PDI Word 3 : User Defined Function

The function of this data word can be selected by the user using drive parameter P5-14. The possible setting options are shown below :-

0: Torque limit/reference (BFI-P2 Only) – This option must be selected if the drive output torque limit / setpoint is to be controlled from the fieldbus. This also requires setting P4-06 = 3. The input data is a 16bit unsigned integer including one decimal place. For example, a value of 500 represents a torque setpoint to the BFI-P2 of 50.0%, value 123 gives 12.3%.

The allowed input value range is from 0 to +2000; however the drive output torque will be limited by the maximum limit set by P4-07.

1: User PID reference register – This option allows the setpoint to the PID controller to be received from the Fieldbus. In order for this option to be used, P9-38 must be set to 1, and the PID User setpoint must not be utilised within the drive PLC function.

2: User register 3 – The value received by the drive in PDI 3 is transferred to User Register 3. This option allows the function of the process data word to be defined in Parameter Group 9. In this case, User Register 3 should not be written to within any PLC function code, although the value can be read.

PDI Word 4: User Defined Function

The function of this data word can be selected by the user using drive parameter P5-13. The possible setting options are shown below :-

0: Fieldbus Ramp Control – This option must be selected if the drive acceleration and deceleration ramps are to be controlled from the fieldbus. P5-07 must also be set to 1 to enable this function.

1: User register 4 – The value received by the drive in PDI 4 is transferred to User Register 4. This option allows the function of the process data word to be defined in Parameter Group 9. In this case, User Register 3 should not be written to within any PLC function code, although the value can be read.

Output Data

This part of the memory contains the real-time drive data returned from the BFI to the network master. The function of the first two data words (PDO 1 and PDO 2) is fixed. The configuration of the remaining two words can be adjusted by the user.

PDO Word 1: Fixed Function : Drive Status & Error Code :

This word contains 2 bytes with information as follows :-

High byte : Gives the drive error (fault) code. (Valid when the drive is tripped)

Low byte : Gives the drive status information, 8 bits which function as follows :-

Bit	Logic 0	Logic 1	Notes
0	Drive Stopped	Drive Running	0: Stop 1: Startsignal on
1	Drive Healthy	Drive Fault (Tripped)	0: Drive Healthy 1: Drive tripped
2	Maintenance Indication (HVAC Only)		0: Auto Mode (IP 20 drives) 1: Hand mode (IP20 drives)
3	Status Safe Torque Off	STO Inhibit	0: Safe Torque inputs activated 1: Safe Torque inputs deactivated
4	Not used		0: Maintenance not required 1: Maintenance required
5	Drive ready to run		0: Not Ready 1: STO ok, Drives is enabled, Drive in Auto mode and Drive is powered up
6 - 7	Not used		

PDO Word 2 : Fixed Function : Output Frequency

This word gives the real time drive output frequency information. The data is a 16bit signed integer with one decimal place. E.g. value 123 means 12.3Hz. Value -234 (0xFF16) means -23.4Hz.

PDO Word 3 User Defined

Data to be transferred in this word can be selected by the User in drive parameter P5-12. The possible settings are as follows :-

- 0: Motor current** – Output current to 1 decimal place, e.g. 100 = 10.0 Amps
- 1: Power (x.xx kW)** Output power in kW to two decimal places, e.g. 400 = 4.00kW
- 2: Digital input status** – Bit 0 indicates digital input 1 status, bit 1 indicates digital input 2 status etc.
- 3: Analog Input 2 Signal Level** - 0 to 1000 = 0 to 100.0%
- 4: Drive Heatsink Temperature** – 0 to 100 = 0 to 100°C
- 5: User register 1** – User Defined Register 1 Value
- 6: User register 2** – User Defined Register 1 Value
- 7: P0-80 value** – User Selected data value.

PDO Word 4 : User Defined

Data to be transferred in this word can be selected by the User in drive parameter P5-08. The possible settings are as follows :-

- 0 : Output Torque (BFI-P2 Only)** – 0 to 2000 = 0 to 200.0%
- 1: Power (x.xx kW)** Output power in kW to two decimal places, e.g. 400 = 4.00kW
- 2: Digital input status** – Bit 0 indicates digital input 1 status, bit 1 indicates digital input 2 status etc.
- 3: Analog Input 2 Signal Level** - 0 to 1000 = 0 to 100.0%
- 4: Drive Heatsink Temperature** – 0 to 100 = 0 to 100°C
- 5: User register 1** – User Defined Register 1 Value
- 6: User register 2** – User Defined Register 1 Value
- 7: P0-80 value** – User Selected data value.